. We shall study "connectedness" in this lecture.

(undirected) A graph G is said to be connected if 4 pairs u and u in V(G), 3 a path from u to u. S-t connectority: Given two vertices s and t, are S and t connected. Via search algorithms (IF sand t are in the same). - Breadth First Search - Depth First Search G₂

10

G3

5= 1

L= 213

L,= {2,3}

L_= {4,5,7,8}



Breadth First Search (BFS):

- · Layer L, Consists of all neighbours ofs
- ofs $\forall j = 2, \text{ Layer L}_j \text{ contains all nodes}$ $\forall j = 2, \text{ Layer L}_j \text{ contains all nodes}$ $\forall that do not belong to U L_i and covered.$ $\forall that do not belong to U L_i and covered.$ $\forall thich have an edge to vertices$ in L_{j+1} . $\forall \text{ Linplicitly there's an ordering / priority over}$ $\forall edges \longrightarrow O(mty) = Running time.$



Obs: BFS naturally gives rise to a rooted tree struct. Obs: If j>1, Layer L; contains those modes that are exactly distance j away from s. > Shortest s-t path. Obs: Two nodes s and t are connected if and only if t belongs to some layer in a BFS that starts from S.

Representing grouphs: • Adjacency matrix: VI=n. VI=n. VI=n. $Space = O(n^2)$ J = Const J = Space VI=n. J = Const $VI=i, j \le n$; $A_{ij} = SI$ if $(v_{ij}, v_{j}) \in E(G)$ c s.t space $nsed \le C.n^2$. O otherwise (n_7, n_6) .

Neighbours of vertex vie is given by the leth sow. 3 20,12¹. 1 1 1 1 \bigcirc 1 0 1 0 0 2 1010 3 4 1 01 0 1 5 0 1 \mathbf{O} 1 \mathbb{O}

Depth First Search.

- Strategy is to explore through "leading edges' until you hat a "deadend" and backtrack to a node w/ unexplored neighbours.

Global knowledge. R====3







Obs: We are bridding a tree- Depth First Search tree.